



HITACHI

L300P Series Inverter

Instruction Manual Supplement

For Inverters with Model Suffix of -LBRM or -HBRM

This supplement is to be used together with the
L300P Series Inverter Instruction Manual (NB604XA)

The functions and settings in this supplement supercede
those in the L300P Instruction Manual.

Manual Number: NBZ601DX

After reading this manual, keep it
handy for future reference.

Hitachi Industrial Equipment Systems Co., Ltd.

Revision History

No.	Revision Contents	The Date of Issue	Operation Manual No.
1	Initial Release	Oct. 1999	NBZ601AX
2	Change of Factory Default Settings	Sep. 2000	NBZ601CX
3	Revised by HAL	Jun. 2002	NBZ601DX

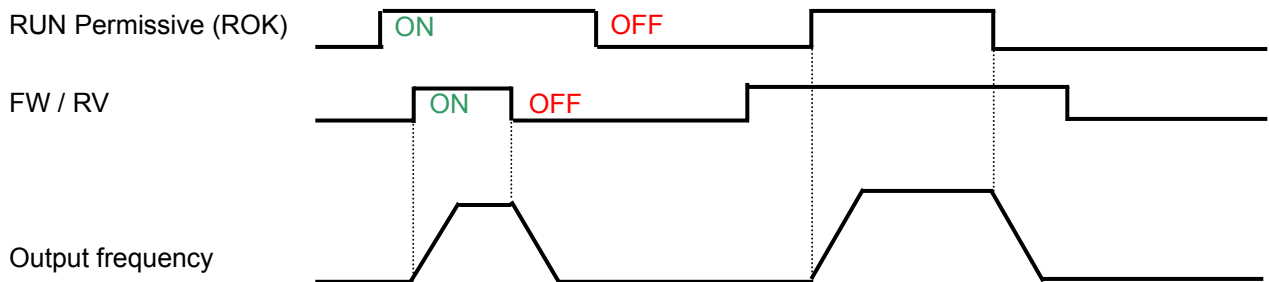
1. Added functions

RUN Permissive input signal for FW/REV [ROK]

- Assign function 49 (ROK) to an intelligent input terminal.
- When inverter is in the STOP mode, and the RUN Permissive input signal [ROK] is "ON," the inverter can enter RUN mode via FW or RV signals
- When inverter is in the STOP mode, and the RUN Permissive input signal [ROK] is "OFF," the FW and RV terminals are disabled, and the inverter cannot enter the RUN mode.
- When inverter is in the RUN mode and Permissive input signal [ROK] transitions from "ON" to "OFF," the inverter will decelerate to a stop.

Related Functions

C001-C005 : Intelligent input setting



Required Parameter Settings: parameter C001 to C005 (intelligent inputs 1 to 5)

Option Code Setting: RUN Permissive input signal for FW/REV = **49** [ROK]

Output signal for RUN Command Source [RMD]

- Assign function 27 [RMD] to an intelligent input terminal.
- When the RUN command source is set to Remote operator, (meaning A002 = 02), the RUN Command Source Output Signal [RMD] is "ON".
- When the RUN Command Source is **NOT** the Remote operator, (A002 is NOT = 02) the RUN Command Source Output Signal [RMD] is "OFF".

Related Functions

C021-C022 : Intelligent output setting
 C026 : Alarm relay output setting
 A002 : RUN command source

Required Parameter Settings: parameter C021, C022, or C026 (Intelligent outputs 11 or 12, or alarm relay)

Option Code Setting: RUN Command Source output signal = **27** [RMD]

Inverter Action on Loss of Analog Frequency Reference Input Signal

Set parameter P050

When the frequency reference is set by the O, OI, or O2 analog input, if the reference signal remains less than start frequency (parameter b082) level for more than 500 ms, the inverter assumes that the O, OI, or O2 input was lost. Depending on the setting of parameter P50, the inverter will run at a preset frequency according to the options defined in the following table. Subsequently, if the frequency reference from O, OI, or O2 input rises higher than the start frequency (parameter b082) and remains at that level for more than 500 ms, the inverter will assume that the O, OI, or O2 input was re-established and resume normal operation.

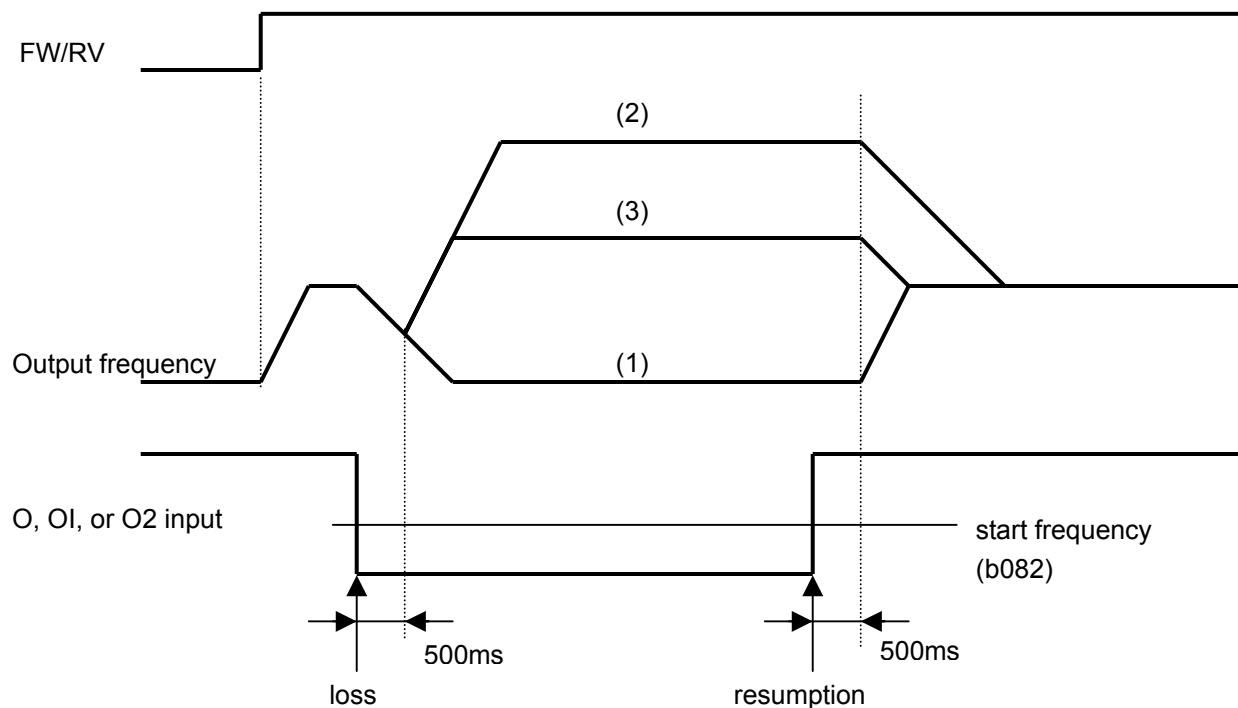
Related Functions

P020 : Freq. During Loss of O/OI/O2

A020/A220 : 1st/2nd/multi-stage speed

b082 : Start frequency adjustment

Set item	Function code	Set value	Description
Frequency during the loss of O, OI, or O2 input	P050	00	Function disabled
		01	Frequency = 0 Hz (1)
		02	Frequency = maximum frequency (2)
		03	Frequency = 1 st /2 nd /multi-stage speed (parameter No.A020/A220) (3)



2. Function Parameter list

Monitor mode

Display code	Function name	Monitor or Data Range (digital operator)
d001	Output Frequency Monitor	0.00-99.99/100.0-400.0 (Hz)
d002	Output Current Monitor	0.0-999.9 (A)
d003	Rotation Direction Monitor	F(forward)/o(stop)/r(reverse)
d004	Process Variable (PV) PID Feedback Monitor	0.00-99.99/100.0-999.9/1000. -9999. / 1000-9999/{100-999 (10000-99900)}
d005	Input Terminal Status	
d006	Intelligent Output Terminal Status	
d007	Scaled Output Frequency Monitor	0.00-99.99/100.0-999.9/1000. -9999. / 1000-3996
d013	Output Voltage Monitor	0.0-600.0 (V)
d014	Input Power monitor	0.0-999.9 (kW)
d016	Cumulative operation RUN time monitor	0.-9999./1000-9999/{100-999 (hr)}
d017	Cumulative Power ON Time Monitor	0.-9999./1000-9999/{100-999 (hr)}
d080	Trip Counter	0.-9999./1000-6553(10000-65530) (time)
d081	Trip monitor 1	Factor, frequency (Hz), current (A), voltage (V), RUN time (hr), power ON time (hr)
d082	Trip monitor 2	Factor, frequency (Hz), current (A), voltage (V), RUN time (hr), power ON time (hr)
d083	Trip monitor 3	Factor, frequency (Hz), current (A), voltage (V), RUN time (hr), power ON time (hr)
d084	Trip monitor 4	Factor, frequency (Hz), current (A), voltage (V), RUN time (hr), power ON time (hr)
d085	Trip monitor 5	Factor, frequency (Hz), current (A), voltage (V), RUN time (hr), power ON time (hr)
d086	Trip monitor 6	Factor, frequency (Hz), current (A), voltage (V), RUN time (hr), power ON time (hr)
d090	Programming Error Monitor	Warning code

Function Mode

Display code	Function name	Monitor or Data Range (digital operator)	LBRM/ HBRM Initial Data	LFU/HFU Initial Data
F001	Output frequency	0.0, starting frequency to Maximum frequency (Hz)	15.00 NOTE (1)	0.00
F002	Acceleration (1) time	0.01-99.99/100.0-999.9/1000.-3600.(s)	60.00	30.00
F202	Acceleration (2) time	0.01-99.99/100.0-999.9/1000. -3600. (s)	60.00	30.00
F003	Deceleration (1) time	0.01-99.99/100.0-999.9/1000. -3600. (s)	90.00	30.00
F203	Deceleration (2) time	0.01-99.99/100.0-999.9/1000. -3600. (s)	90.00	30.00
F004	Keypad Run Key Routing	00(forward)/01(reverse)	00	00

NOTE (1) : This value appears because lower limiter (A062, A262) is set to 15Hz.

Function Mode

Code		Function name	Setting range	LBRM/HFBM Initial Data	LFU/HFU Initial data
Base setting	A001	Frequency setting selection	00(VR)/01(terminal)/02(operator)/03(RS485)/04(option1)/05(option2)	01	01
	A002	Operation setting selection	01(terminal)/02(operator)/03(RS485)/04(option1)/05(option2)	01	01
	A003	Base frequency,	30. - maximum. frequency (Hz)	60.	60.
	A203	Base frequency, 2nd motor	30. - 2 nd braking maximum. frequency (Hz)	60.	60.
	A004	Maximum frequency	30. - 400. (Hz)	60.	60.
	A204	Maximum frequency, 2nd motor	30. - 400. (Hz)	60.	60.
Analog input setting	A005	AT terminal selection	00(Changing of O and OI with AT terminal)/01(Changing of O and O2 with AT terminal)	00	00
	A006	O2 selection	00(single)/01(auxiliary speed of O, OI) [no reversible]/02(auxiliary speed of O, OI [reversible]	00	00
	A011	O start	0.00-99.99/100.0-400.0 (Hz)	0.00	0.00
	A012	O end	0.00-99.99/100.0-400.0 (Hz)	60.00	0.00
	A013	O start rate	0.-100.0 (%)	0.	0.
	A014	O end rate	0.-100.0(%)	100.	100.
	A015	O start selection	00 (external starting frequency)/01(0Hz)	01	01
	A016	O, OI, O2 sampling	1.-30.(times)	8.	8.
Multistage speed · jogging frequency setting	A019	Multi-speed selection	00(binary : range is to 16 stage speed with 4 terminals)/01(bit : range is to 6 stage speed with 5 terminals)	00	00
	A020	Multi-speed 0	0.00, starting frequency-maximum. frequency(Hz)	NOTE (1) 15.00	0.00
	A220	Multi-speed 0, 2 nd motor	0.00, starting frequency-2 nd braking maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A021	Multi-speed1	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A022	Multi-speed2	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A023	Multi-speed3	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A024	Multi-speed4	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A025	Multi-speed5	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A026	Multi-speed6	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A027	Multi-speed7	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A028	Multi-speed8	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A029	Multi-speed9	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A030	Multi-speed10	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A031	Multi-speed11	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A032	Multi-speed12	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A033	Multi-speed13	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A034	Multi-speed14	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A035	Multi-speed15	0.00, starting frequency-maximum frequency(Hz)	NOTE (1) 15.00	0.00
	A038	Jogging frequency	0.00, starting frequency-9.99(Hz)	1.00	1.00
	A039	Jogging selection	00(free-run on JG stop / invalid on running) / 01(stop decelerating on JG stop / invalid on running) / 02(DC braking on JG stop/invalid on running) / 03(free-run on JG stop/valid on running [JG after stop decelerating]) / 04 (stop decelerating on JG stop/valid on running) / 05 (DC braking on JG stop/valid on operating)	00	00

Function Mode

Code	Function name	Setting range	LBRM/HFBM Initial Data	LFU/HFU Initial data	
V/f characteristic	A041	Torque boost selection	00 (manual torque boost) / 01 (automatic torque boost)	00	00
	A241	Torque boost selection, 2 nd motor	00 (manual torque boost) / 01 (automatic torque boost)	00	00
	A042	Manual torque boost	0.0-20.0(%)	1.0	1.0
	A242	Manual torque boost, 2 nd Motor	0.0-20.0(%)	1.0	1.0
	A043	Manual torque boost point	0.0-50.0(%)	5.0	5.0
	A243	Manual torque boost point, 2 nd motor	0.0-50.0(%)	5.0	5.0
	A044	1 st control	00/(VC)/01(VP1.7power)/02(free V/f setting)	01	00
	A244	2 nd control	00/(VC)/01(VP1.7power)/02(free V/f setting)	01	00
	A045	Output voltage gain	20. - 100.	100.	100.
Direct current braking	A051	DC braking selection	00(invalid)/01(valid)	00	00
	A052	DC braking frequency	0.00-60.00(Hz)	0.50	0.50
	A053	DC braking wait time	0.0 - 5.0(s)	0.0	0.0
	A054	DC braking power	0. - 70. (%)	0.	0.
	A055	DC braking time	0.0 - 60.0(s)	0.0	0.0
	A056	DC braking edge/level Selection	00(edge action) / 01(level action)	01	01
	A057	DC braking power (starting time)	0. - 70. (%)	0.	0.
	A058	DC braking time(starting time)	0.00-60.0(s)	0.0	0.0
	A059	DC carrier frequency	0.5-12(kHz) Derating	3.0	3.0

Function Mode

Code	Function name	Setting range	LBRM/HFBM Initial Data	LFU/HFU Initial data	
Upper and lower limiter-jump Frequency	A061	1 st frequency upper limiter	0.00, 1 st frequency lower limiter-maximum frequency(Hz)	60.00	0.00
	A261	2 nd frequency upper limiter	0.00 , 2 nd frequency lower limiter-2 nd setting maximum frequency(Hz)	60.00	0.00
	A062	1 st frequency lower limiter	0.00 , start frequency-maximum frequency(Hz)	15.00	0.00
	A262	2 nd frequency lower limiter	0.00 , start frequency-2 nd setting maximum frequency(Hz)	15.00	0.00
	A063	Jump frequency1	0.00-99.99/100.0-400.0(Hz)	0.00	0.00
	A064	Jump frequency band1	0.00-10.00(Hz)	0.50	0.50
	A065	Jump frequency2	0.00-99.99/100.0-400.0(Hz)	0.00	0.00
	A066	Jump frequency band2	0.00-10.00(Hz)	0.50	0.50
	A067	Jump frequency3	0.00-99.99/100.0-400.0(Hz)	0.00	0.00
	A068	Jump frequency band3	0.00-10.00(Hz)	0.50	0.50
PID control	A069	Acceleration stop frequency	0.00-99.99/100.0-400.0(Hz)	0.00	0.00
	A070	Acceleration stop time	0.00-60.0(s)	0.0	0.0
	A071	PID selection	00(invalid)/01(valid)	00	00
	A072	PID P gain	0.2-5.0	1.0	1.0
	A073	PID I gain	0.0-3600.(s)	1.0	1.0
	A074	PID D gain	0.00-100.0(s)	0.00	0.00
AVR	A075	PID scale	0.01-99.99(%)	1.00	1.00
	A076	PID feedback selection	00(feedback : OI)/01(feedback : O)	00	00
Operation mode/ adjustable function	A081	AVR selection	00(ON always)/01(OFF always)/02(OFF on decelerating)	00	00
	A082	Motor voltage selection	200/215/220/230/240 , 380/400/415/440/460/480(V)	230/460	230/460
	A085	Operation mode selection	00(normal operation)/01(energy-saving operation)	00	00
	A086	Energy-saving response accuracy adjustment	0.0-100.0(s)	50.0	50.0
	A092	Acceleration time2	0.01-99.99/100.0-999.9/1000.-3600.(s)	60.00	15.00
	A292	Acceleration time2(2 nd motor)	0.01-99.99/100.0-999.9/1000.-3600.(s)	60.00	15.00
	A093	Deceleration time2	0.01-99.99/100.0-999.9/1000.-3600.(s)	90.00	15.00
	A293	Deceleration time2(2 nd motor)	0.01-99.99/100.0-999.9/1000.-3600.(s)	90.00	15.00
	A094	2 nd stage adjustable selection	00(change with 2CH terminal)/01(change with setting)	00	00
	A294	2 nd stage adjustable selection(2 nd motor)	00(change with 2CH terminal)/01(change with setting)	00	00
	A095	2 nd acceleration frequency	0.00-99.99/100.0-400.0(Hz)	0.00	0.00
	A295	2 nd acceleration frequency(2 nd motor)	0.00-99.99/100.0-400.0(Hz)	0.00	0.00
	A096	2 nd deceleration frequency	0.00-99.99/100.0-400.0(Hz)	0.00	0.00
	A296	2 nd deceleration frequency (2 nd motor)	0.00-99.99/100.0-400.0(Hz)	0.00	0.00
External frequency adjustment	A097	Acceleration pattern selection	00(straight line)/01(S-curve)/02(U-curve)/03(reverse U-curve)	00	00
	A098	Deceleration pattern selection	00(straight line)/01(S-curve)/02(U-curve)/03(reverse U-curve)	00	00
	A101	O1 start	0.00-99.99/100.0-400.0(Hz)	0.00	0.00
	A102	O1 end	0.00-99.99/100.0-400.0(Hz)	60.00	0.00
	A103	O1 start rate	0.-100. (%)	20.	20.
	A104	O1 end rate	0.-100. (%)	100.	100.
	A105	O1 start selection	00(external start frequency)/01(0Hz)	01	01
	A111	O2 start	-400.--100./-99.9-0.00-99.9/100.-400.(Hz)	-60.00	0.00
	A112	O2 end	-400.--100./-99.9-0.00-99.9/100.-400.(Hz)	60.00	0.00
	A113	O2 start rate	-100. - 100. (%)	-100.	-100.
Accel, Decel	A114	O2 end rate	-100. - 100. (%)	100.	100.
	A131	Acceleration curve constant	01(small swelling)-10(large swelling)	02	02
Instantaneous power failure restart	A132	Deceleration curve constant	01(small swelling)-10(large swelling)	02	02
	b001	Retry selection	00(trip)/01(Ohz start)/02(start after equal frequency)/03(trip after equaling frequency and deceleration stop)	02	00
	b002	Allowable under-voltage power failure time	0.3-1.0(s)	1.0	1.0
	b003	Retry wait time	0.3-100.(s)	1.0	1.0
	b004	Instantaneous power failure/ under-voltage trip during stop	00(invalid)/01(valid)/02(invalid during stop and deceleration by stop command)	00	00
	b005	Instantaneous power failure/ under-voltage retry time selection	00(16 times)/01(free)	00	00
	b006	Open-phase selection	00(invalid)/01(valid)	00	00
b007	Frequency setting to match	0.00-99.99/100.0-400.0(Hz)	0.00	0.00	

Function mode

Code	Function name	Setting range	LBRM/HFBM Initial Data	LFU/HFU Initial data	
Electronic thermal	b012	Electronic thermal level	0.2*constant current-1.20*constant current(A)	Rated current of inverter 1.20	Rated current of inverter
	b212	Electronic thermal level (2 nd motor)	0.2*constant current-1.20*constant current(A)	Rated current of inverter 1.20	Rated current of inverter
	b013	Electronic thermal characteristic selection	00/(reduced characteristic)/01(constant characteristic)/02(free setting)	00	01
	b213	Electronic thermal characteristic selection (2 nd motor)	00/(reduced characteristic)/01(constant torque characteristic)/02(free setting)	01	01
	b015	Free electronic thermal frequency1	0.-400.(Hz)	0.	0.
	b016	Free electronic thermal current1	0.0-1000.(A)	0.0	0.0
	b017	Free electronic thermal frequency2	0.-400.(Hz)	0.	0.
	b018	Free electronic thermal current2	0.0-1000.(A)	0.0	0.0
	b019	Free electronic thermal frequency3	0.-400.(Hz)	0.	0.
	b020	Free electronic thermal current3	0.0-1000.(A)	0.0	0.0
Overload restriction	b021	Overload restriction selection	00(invalid)/01(enabled on acceleration · constant speed)/02(enabled on constant speed)	01	01
	b022	Overload restriction level	0.50* rated current-1.50* rated current(A)	Rated Current of inverter ×1.20	Rated Current of inverter ×1.20
	b023	Overload restriction limit constant	0.10-30.00(s)	10.00	1.00
	b024	Overload restriction 2 selection	00(invalid)/01(valid on acceleration · constant speed)/02(valid on constant speed)	01	01
	b025	Overload restriction level2	0.50*rated current-1.50*rated current(A)	Rated current of inverter 1.20	Rated current of inverter ×1.20
	b026	Overload restriction constant2	0.10-30.00(s)	1.00	1.00
	b031	Software lock mode selection	00(impossible to change the data except this item on SFT terminal ON)/01(impossible to change the data except setting frequency item on SFT terminal is ON)/02(impossible to change the data except this item)/03(impossible to change the data except setting frequency item)/10(possible to change data on operating)	01	01
Free V/f setting	b100	Free V/f frequency1	0.- Free V/f frequency2(Hz)	0.	0.
	b101	Free V/f voltage1	0.-800.0(V)	0.0	0.0
	b102	Free V/f frequency2	0.- Free V/f frequency3(Hz)	0.	0.
	b103	Free V/f voltage 2	0.-800.0(V)	0.0	0.0
	b104	Free V/f frequency3	0.- Free V/f frequency4(Hz)	0.	0.
	b105	Free V/f voltage 3	0.-800.0(V)	0.0	0.0
	b106	Free V/f frequency4	0.- Free V/f frequency5(Hz)	0.	0.
	b107	Free V/f voltage 4	0.-800.0(V)	0.0	0.0
	b108	Free V/f frequency5	0.- Free V/f frequency6(Hz)	0.	0.
	b109	Free V/f voltage 5	0.-800.0(V)	0.0	0.0
	b110	Free V/f frequency6	0.- Free V/f frequency7(Hz)	0.	0.
	b111	Free V/f voltage 6	0.-800.0(V)	0.0	0.0
	b112	Free V/f frequency7	0.-400.(Hz)	0.	0.
b113	Free V/f voltage 7	0.-800.0(V)	0.0	0.0	

Function Mode

Code	Function name	Setting range	LBRM/HFBM Initial Data	LFU/HFU Initial data	
Intelligent input terminal setting	C001	Intelligent input1 setting	01/(RV:Reverse Run/Stop)/02(CF1:Multi-speed1)/03(CF2:Multi-speed2)/ 04(CF3:Multi-speed3)/05(CF4:Multi-speed4)/06(JG:Jogging)/ 07(DB:External DC braking)/08(SET:2 nd control)/ 09(2CH:two-stage adjustable speed)/ 11(FRS:Free-run)/12(EXT:External trip)/ 13(USP:Unattended start protection)/14(CS:commercial change)/ 15(SFT:software lock)/16(AT:Analog input voltage/current select)/ 18(RS:Reset inverter)/20(STA:3wire run)/21(STP:3wire keep)/ 22(F/R:3wire forward/reverse)/23(PID:PID selection valid/invalid) / 24(PIDC:PID integrating reset)/ 27(UP:Remote control UP function)/28(DWN:Remote control DOWN function)/ 29(UDC:Remote control data clear)/32(SF1:Multi-speed bit1)/ 33(SF2:Multi-speed bit2)/34(SF3:Multi-speed bit3)/35(SF4:Multi-speed bit4)/ 36(SF5:Multi speed bit5)/37(SF6:Multi-speed bit6)/38(SF7:Multi-speed bit7)/ 39(OLR:Overload restriction change)/no(NO:No assign) 49(ROK: permissive input signal for FW/REV) NOTE (2)	18	18
	C002	Intelligent input2 setting		16	16
	C003	Intelligent input3 setting		49	13
	C004	Intelligent input4 setting		02	02
	C005	Intelligent input5 setting		01	01

NOTE (2) : See Page 1(ROK: RUN Permissive input signal for FW/REV)

Function mode

Code	Function name	Setting range	LBRM/HFBM Initial Data	LFU/HFU Initial data	
Input terminal setting Intelligent	C011	Intelligent input1a/b(NO/NC) selection	00(NO)/01(NC)	00	00
	C012	Intelligent input2a/b(NO/NC) selection	00(NO)/01(NC)	00	00
	C013	Intelligent input3a/b(NO/NC) selection	00(NO)/01(NC)	00	01
	C014	Intelligent input4a/b(NO/NC) selection	00(NO)/01(NC)	00	00
	C015	Intelligent input5a/b(NO/NC) selection	00(NO)/01(NC)	00	00
	C019	Input FWa/b(NO/NC) selection	00(NO)/01(NC)	00	00
Output terminal state setting : Output level setting	C021	Intelligent output 11 setting	00(RUN:running)/01(FA1:Frequency arrival type1 signal)/	27	01
	C022	Intelligent output 12 setting	02(FA2:frequency arrival type2 signal)/	00	00
	C026	Alarm relay output setting	03(OL:Overload advance notice signal)/ 04(OD:Output deviation for PID control)/ 05(AL:Alarm signal)/06(FA3:Only setting frequency)/ 08(IP:On instantaneous stop)/09(UV:Under voltage)/ 11(RNT:RUN time over)/ 12(ONT:ON time over)/13(THM:thermal caution)/ 27(RMD: RUN command source) NOTE (3)	05	05
	C027	FM selection	00(Output frequency)/01(Output current) / 03(Digital output frequency)/04(Output voltage)/ 05(Output electric power)/06(thermal load rate)/07(LAD frequency)	00	00
	C028	AM selection	00(Output frequency)/01(Output current)/04(Output voltage)/ 05(Output electric power)/06(thermal load rate)/07(LAD frequency)	00	00
	C029	AMI selection	00(Output frequency)/01(Output current)/04(Output voltage)/ 05(Output electric power)/06(Thermal load rate)/07(LAD frequency)	00	00
Communication function adjustment	C031	Intelligent output 11a/b	00(NO)/01(NC)	00	00
	C032	Intelligent output 12a/b	00(NO)/01(NC)	00	00
	C036	Alarm relay output a/b	00(NO)/01(NC)	00	01
	C040	Overload advance notice signal output mode	00(On accel. And decel, constant speed)/ 01(Only constant speed)	01	01
	C041	Overload notice level	0.0-2.0*rated current(A)	Inverter rated current	Inverter rated current
	C042	Frequency arrival setting for accel.	0.00-99.99/100.0-400.0(Hz)	0.00	0.00
	C043	Arrival frequency setting for decel.	0.00-99.99/100.0-400.0(Hz)	0.00	0.00
	C044	PID deviation setting level	0.0-100.0(%)	3.0	3.0
	C061	Electrical thermal protection warning level setting	0.-100.(%)	80.	80.
Analog meter setting	C070	Data command	02(operator)/03(RS485)/04(option1)/05(option2)	02	02
	C071	Communicating transmission speed	02(TEST)/03(2400bps)/04(4800bps)/05(9600bps)/06(19200bps)	04	04
	C072	Communication code	1.-32.	1.	1.
	C073	Communication bit	7(7bit)/8(8bit)	7	7
	C074	Communication parity	00(no parity name)/01(even parity)/02(odd parity)	00	00
	C075	Communication stop bit	1(bit)/2(bit)	1	1
	C078	Communication waiting time	0.-1000.(ms)	0.	0.
C081	O adjustment	0.-9999./1000-6553(10000-65530)	Setting on forwarding	Setting on forwarding	
C082	O1 adjustment	0.-9999./1000-6553(10000-65530)	Setting on forwarding	Setting on forwarding	
C083	O2 adjustment	0.-9999./1000-6553(10000-65530)	Setting on forwarding	Setting on forwarding	
C085	Thermistor adjustment	0.0 - 1000.	105.0	105.0	
C086	AM offset adjustment	0.0 - 10.0(V)	0.0	0.0	
C087	AMI adjustment	0. - 255.	80	80	
C088	AMI offset adjustment	0. - 20.0(mA)	4.0	4.0	

NOTE (3) : See Page 1 (RMD : Output signal for RUN Command Source)

Function mode

Code	Function name	Setting range	LBRM/HFBM Initial Data	LFU/HFU Initial data	
The others	b034	RUN time/Power ON time level	0.-9999./1000-6553(10000-65530)hr	0.	0.
	b035	Operation direction restrict	00(Reverse is valid)/01(Only forward)/02(Only reverse)	00	00
	b036	Start reduced voltage	00(Start reduced voltage time small)-06(Start reduced voltage time large)	06	06
	b037	Display selection	00(all display)/01(each function display)/02(User setting , main setting)	00	00
	b080	AM adjustment	0. - 255.	180	180
	b081	FM adjustment	0. - 255.	60	60
	b082	Start frequency adjustment	0.10-9.99(Hz)	0.50	0.50
	b083	Carrier frequency setting	0.5-12.0(kHz) Derating enable,	3.0	3.0
	b084	Initialize mode	00(Trip history clear)/01(Data initialization)/02(Trip history clear + data initialization)	00	00
	b085	Country code for initialization	00(Interior)/01(EC)/02(USA)	02	02
	b086	Frequency scalar conversion factor	0.1-99.9	1.0	1.0
	b087	STOP key enable	00(valid)/01(Invalid)	00	00
	b088	Resume on FRS cancellation mode	00(0Hz start)/01(Start f-equaling)	00	00
	b090	BRD usage ratio	0.0-100.0(%)	0.0	0.0
	b091	Stop mode selection	00(deceleration stop)/01(Free-run stop)	01	00
	b092	Cooling fan control	00(Always ON)/01(ON during run <After power ON, then for 5 minutes on stop is implied.>)	00	00
	b095	BRD selection	00(Invalid)/01(valid<Invalid during stop>)/02(valid<Valid during stop>)	00	00
	b096	BRD ON level	330-380/660-760(V)	360/720	360/720
	b098	Thermistor selection	00(Invalid)/01(Positive temperature coefficient enable)/02 (NTC enable)	00	00
	b099	Thermistor error level	0. - 9999. (ohm)	3000.	3000.
	C091	Debug mode selection	00(No display)/01(Display)	00	00
	C101	UP/DWN selection	00(No frequency data)/01(Keep frequency data)	00	00
	C102	Reset selection	00(Trip cancel during ON)/01(Trip cancel during OFF)/02(Valid only during trip <Cancel during ON>)	00	00
	C103	Reset f frequency matching selection	00(0Hz start)/01(Start f-equaling)	01	00
	C121	O zero adjustment	0.-9999./1000-6553(10000-65530)	Set on forwarding	Set on forwarding
	C122	O1 zero adjustment	0.-9999./1000-6553(10000-65530)	Set on forwarding	Set on forwarding
	C123	O2 zero adjustment	0.-9999./1000-6553(10000-65530)	Set on forwarding	Set on forwarding
	H003	1 st motor capacity selection	0.20-75.0(kW)	Set on forwarding	Set on forwarding
	H203	2 nd motor capacity selection	0.20-75.0(kW)	Set on forwarding	Set on forwarding
	H004	1 st motor pole selection	2/4/6/8(pole)	4	4
H204	2 nd motor pole selection	2/4/6/8(pole)	4	4	
H006	1 st stabilized factor	0. - 255.	100.	100.	
H206	2 nd stabilized factor	0. - 255.	100.	100.	
P001	Option1 operation selection on error	00(TRP)/01(RUN)	00	00	
P002	Option2 operation selection on error	00(TRP)/01(RUN)	00	00	
P031	Input mode selection for Digital input option	00(Mode 0)/01(Mode 1)/02(Mode 2)	00	00	
P050	Frequency during the loss of O,O2,O1 input	00(Invalid)/01(0Hz)/02(maximum Frequency)/03(multi speed 0) NOTE (1)	00	00	
U001	User1 selection	no/d001-P050	no	no	
U002	User2 selection	no/d001-P050	no	no	
U003	User3 selection	no/d001-P050	no	no	
U004	User4 selection	no/d001-P050	no	no	
U005	User5 selection	no/d001-P050	no	no	
U006	User6 selection	no/d001-P050	no	no	
U007	User7 selection	no/d001-P050	no	no	
U008	User8 selection	no/d001-P050	no	no	
U009	User9 selection	no/d001-P050	no	no	
U010	User10 selection	no/d001-P050	no	no	
U011	User11 selection	no/d001-P050	no	no	
U012	User12 selection	no/d001-P050	no	no	

NOTE (4) : See Page 2 (When O, O1, or O2 frequency reference input signal is lost)

3. Standard specification list

(1) 200V class

Inverter Model	L300P-004LFU	L300P-007LFU	L300P-015LFU	L300P-022LFU	L300P-037LFU	L300P-055LFU	L300P-075LFU	L300P-110LFU	L300P-150LFU	L300P-185LFU	L300P-220LFU	L300P-300LFU	L300P-370LFU	L300P-450LFU	L300P-550LFU	
Protection structure (note1)	IP20(NEMA1)															
Max. Applicable Motor 4P (kW) (note2)	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	
Rated input Alternating voltage(kVA)	200V	1.0	1.5	2.5	3.6	5.7	8.3	11.0	15.2	20.0	25.2	29.4	39.1	48.4	58.5	72.7
	240V	1.2	2.0	3.1	4.3	6.8	9.9	13.3	18.2	24.1	30.3	35.3	46.9	58.1	70.2	87.2
Rated input alternating voltage	Three-phase 200-240V (+10%) 50Hz/60Hz															
Rated output voltage (note3)	Three-phase 200-240V (This corresponds to receiving voltage.)															
Rated output current (A)	3	5	7.5	10.5	16.5	24	32	44	58	73	85	113	140	169	210	

(2) 400V class

Inverter Model	-	L300P-007HFU	L300P-015HFU	L300P-022HFU	L300P-037HFU	L300P-055HFU	L300P-075HFU	L300P-110HFU	L300P-150HFU	L300P-185HFU	L300P-220HFU	L300P-300HFU	L300P-370HFU	L300P-450HFU	L300P-550HFU	
Protection structure (note1)	IP20(NEMA1)															
Max. Applicable Motor 4P (kW) (note2)	-	0.75	0.15	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	
Rated input Alternating voltage(kVA)	400V	-	1.5	2.5	3.6	5.7	8.3	11.0	15.2	20.0	25.6	29.7	39.4	48.4	58.8	72.7
	480V	-	2.0	3.1	4.3	6.8	9.9	13.3	18.2	24.1	30.7	35.7	47.3	58.1	70.1	87.2
Rated input alternating voltage	Three-phase 380-480V (+10%) 50Hz/60Hz															
Rated output voltage (note3)	Three-phase 380-480V (This corresponds to receiving voltage.)															
Rated output current (A)	-	2.5	3.8	5.3	8.6	12	16	22	29	37	43	57	70	85	105	

(3) Common specification for 200V/400V class

Inverter Model	L300P-004LFU	L300P-007LHFU	L300P-015LHFU	L300P-022LHFU	L300P-037LHFU	L300P-055LHFU	L300P-075LHFU	L300P-110LHFU	L300P-150LHFU	L300P-185LHFU	L300P-220LHFU	L300P-300LHFU	L300P-370LHFU	L300P-450LHFU	L300P-550LHFU	
Control system	Sine-wave modulation PWM system.															
Output frequency range (note4)	0.1-400Hz															
Frequency accuracy	Digital command +/-0.01% for Max. frequency, analog frequency +/-0.2%(25+10C)															
Frequency resolving power	Digital setting: 0.01Hz, analog setting:Max. frequency /4000															
Voltage/frequency characteristic	V/f option variable, V/f control, (constant torque, reduced torque)															
Overload current rate	120% for 60 seconds, 150% for 0.5second															
Acceleration/ deceleration time	0.01-3.600seconds (straight or S-Curve on acceleration, deceleration is optional setting individually), 2 nd adjustable setting is possible.															
Control	Regenerative Control (short duration) (note5)	BRD circuit built-in (Discharge resistance is required.)										Regenerative unit is required.				
	DC Braking	On starting and decelerating by stop command, inverter operates under operation setting frequency. Or inverter operates with external input (Breaking power, time, frequency can be set.)														
Input signal	Frequency	Operator	No Operator													
		Volume	Setting with potentiometer on the digital operator (Built-in as standard) (Analog setting)													
		External Signal	DC 0 to 5V, -5 to +5V, 0 to 10V, -10 to +10V (input impedance 10k ohm), 4-20mA (input impedance 100 ohm)													
		External port	Setting with RS485 communication													
	Run/ Stop	Operator	No Operator													
External signal	Forward Run/Stop (1a connect), reverse command is impossible on assigning of terminal (selection of 1a, 1b is possible), input of 3 wires is possible.															
External port	Setting with RS485.															
Intelligent input terminal	Use by selecting terminals from: Reverse command (RV), multi-speed1-4 (CF1-CF4), jogging (JG), external dc braking (DB), 2 nd control (SET), 2 nd acceleration (2CH), free-run stop (FRS), external trip (EXT), USP function (USP), commercial change (CS), software lock (SFT), analog input voltage / current / select (AT), reset inverter (RS), 3 wire run (STA), 3 wire keep (STP), 3 wire direction selection (F/R), PID selection valid/invalid (PID), PID integrating reset (PIDC), remote control, up function (UP), remote control down function (DWN), remote control data clear (UDC), multi-speed bit 1-7(SF1-SF7), overload restriction change (OLR), permissive input signal for FW/RV(ROK), no assign (NO)															
Thermistor input terminal	1 terminal															
Output	Intelligent output terminal	2 relay outputs (1a contact), relay(1c contact), output relay selection as follows: (selection from during running, on arrival with constant speed, over setting frequency, PID over-deviation, running command distinction)														
	Intelligent monitor output terminal	Analog voltage output, analog current output, pulse line output														
Display monitor	Output frequency, output current, frequency conversion value, trip history, input output terminal state, input electric power, output voltage.															
Other function	V/f free setting (5 points), Upper / lower frequency limiter, Frequency jump, Curve adjustable speed, Manual torque boost level / Braking point, Analog meter adjustment, Starting frequency, Carrier frequency adjustment, Electronic thermal free setting, External start/end (frequency/rate), Analog input selection, Trip retry, Reduced voltage start, Overload restriction															
Carrier frequency range	0.5-12 kHz															
Protection function	Over-current, over-voltage, under-voltage, electronic thermal level, abnormal trouble, ground fault current on starting, instantaneous stop, USP error, open-phase error, control resistor overload, CT error, external trip, communication error															
Usage surrounding	Frequency temperature /Preservation temperature (note6) /humidity	-10 to 40 degrees (note7) / -20 to 65 degrees / 20 to 90% RH (installed with no dew condensation)														
	Vibration (note7)	5.9m / s ² (0.6G), 10-55Hz										2.9m / s ² (0.3G), 10-55Hz				
	Using place	Under 1,000m above sea level, indoors (installed away from corrosive gasses, dust)(note8)														
Paint color	Grey (Munsell 8.5YR6.2 / 0.2)								Blue (D.I.C14 version No.436)							
Options	Remote operator, copy unit, cable for each operator, braking resistor, regenerative control unit, alternating reactor, D.C. reactor, EMC Mains filter, higher harmonic control unit, LCR filter, applied control installation															
Schematic mass (kg)	3.5	3.5	3.5	3.5	3.5	3.5	5	5	5	12	12	12	20	30	30	

(note1) Protective system bases on JME1030.

(note2) Applicable motor indicates HITACHI three-phase motor. When you use other motor, set so that the motor current doesn't exceed the rated current of the inverter.

(note3) Output voltage will reduce when the power voltage is reduced. (Except when AVR function is selected.)

(note4) When you operate motor over 50/60Hz, inquire about the allowable max.revolution time of motor etc. from motor manufacturer.

(note5) Braking resistance isn't installed in the inverter. When the inverter requires a high regenerative torque, use optional braking resistance and regenerative braking unit.

(note6) Protective temperature is temperature during transportation.

(note7) This bases on the test methods of JIS C0911(1984).

(note8) When the inverter is used in a place with dust, we recommend the optional varnish coating specification. Before it is required.